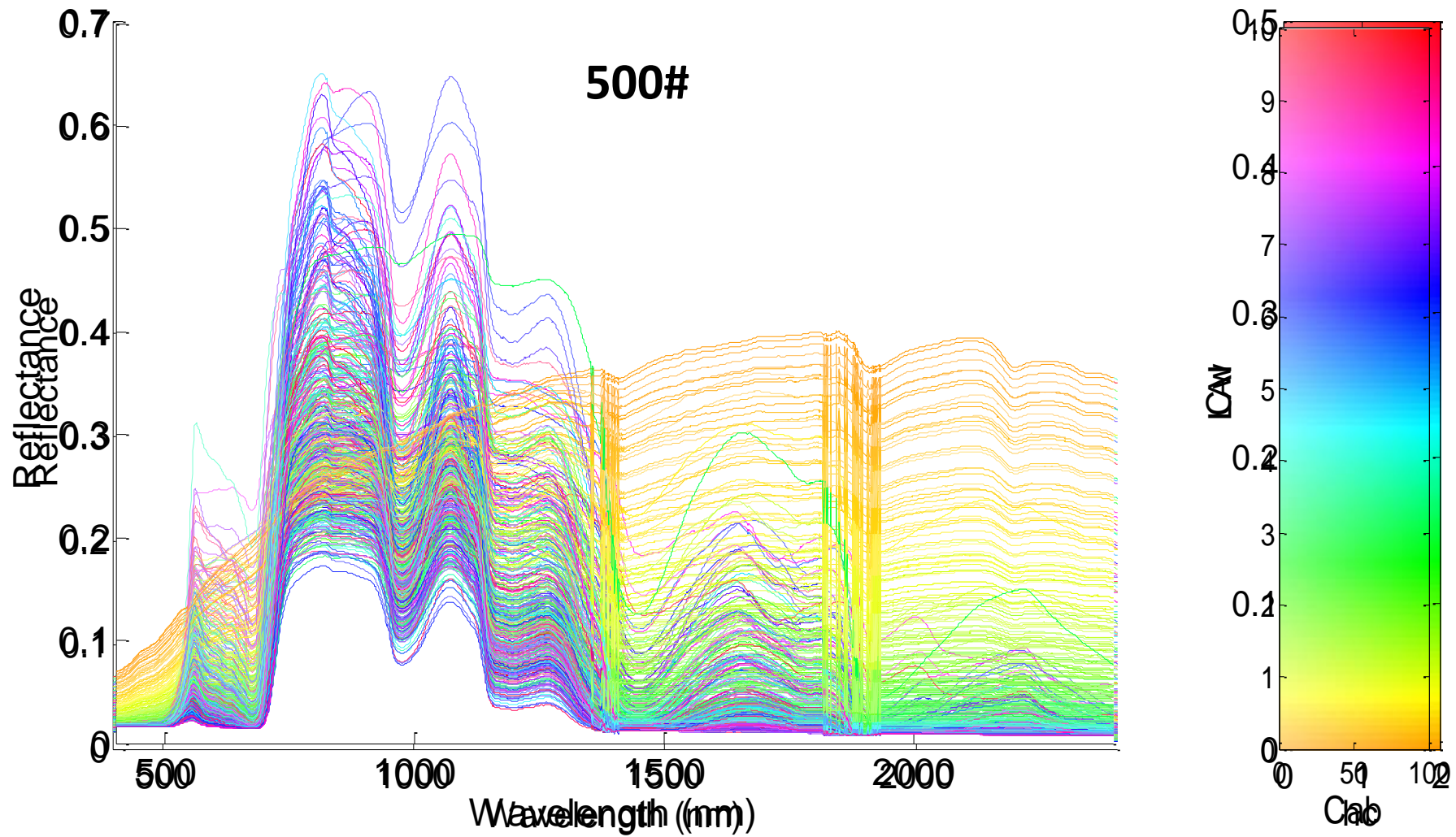




PROGRESS IN EMULATION FOR RADIATIVE TRANSFER MODELING AND MAPPING

Jochem Verrelst, Juan Pablo Rivera, Pablo Morcillo, Maria Lumbieres, Jorge Vicent & Jose Moreno

 Image Processing Laboratory, University of Valencia (Spain)



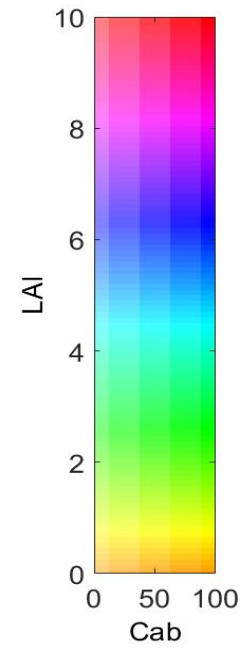
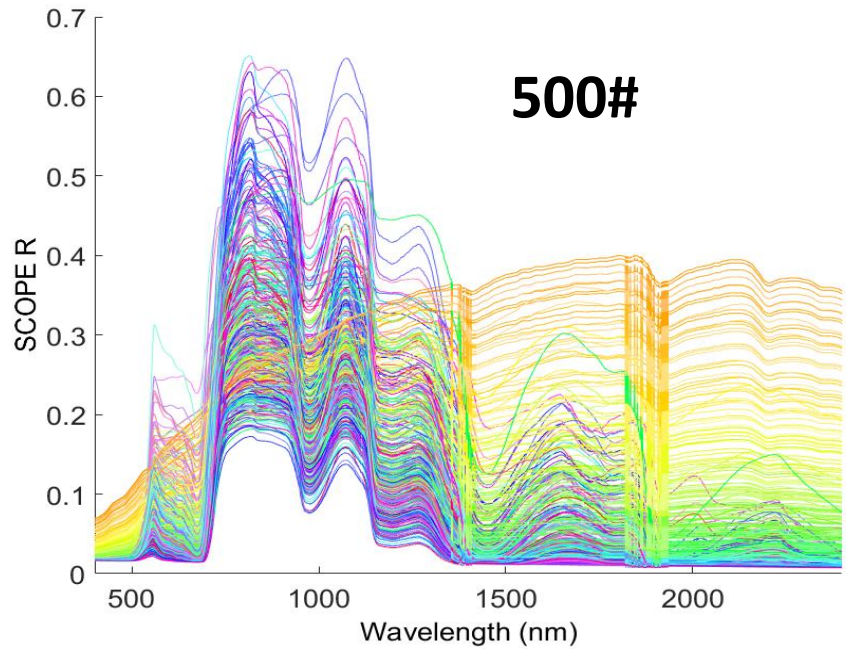
Any difference? Which model would you choose?



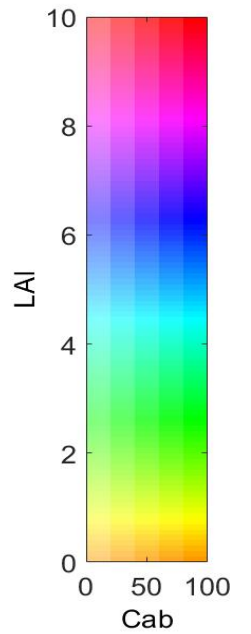
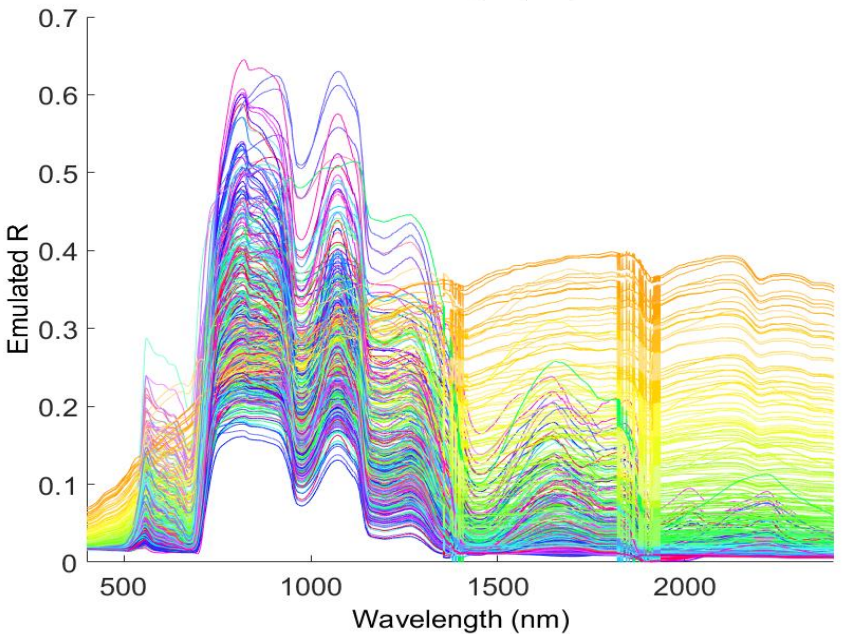
37 min



0.2 s



SCOPE
(RTM)

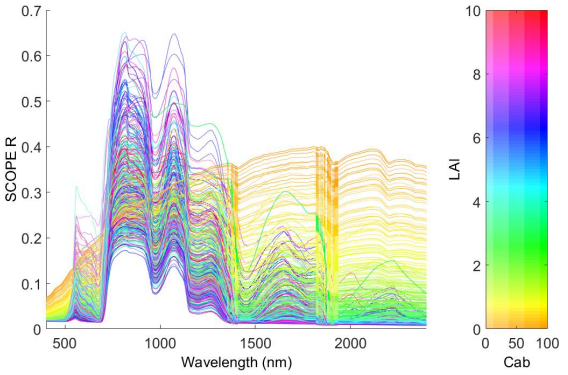
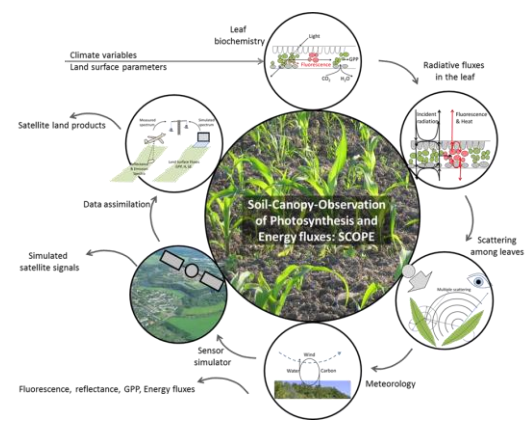


Emulator
(emulated SCOPE)

BACKGROUND

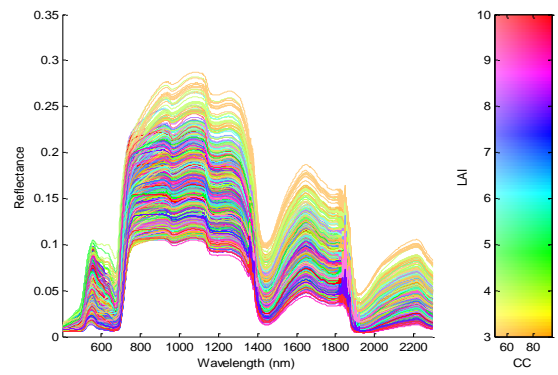
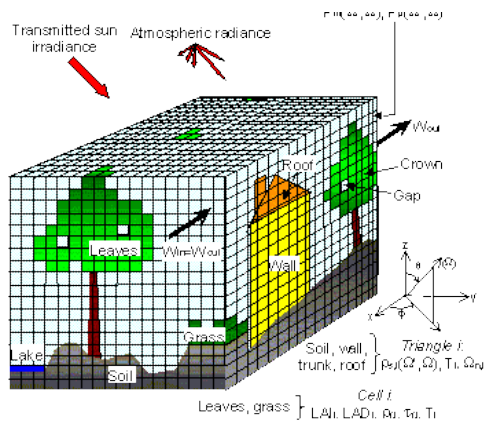
Advanced RTMs: generation of a large LUT (>1000#)

SCOPE



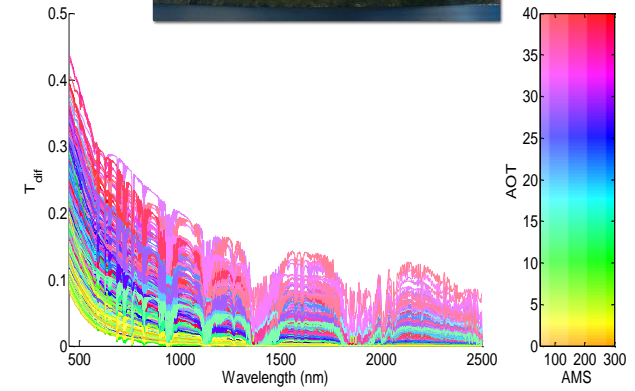
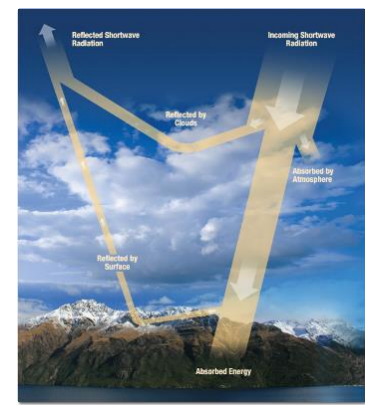
Hours

DART



days

MODTRAN



>days

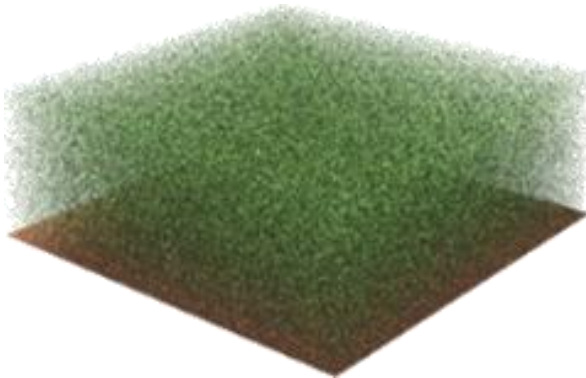
Advanced RTMs: more realistic but slow

Emulation of RTMs

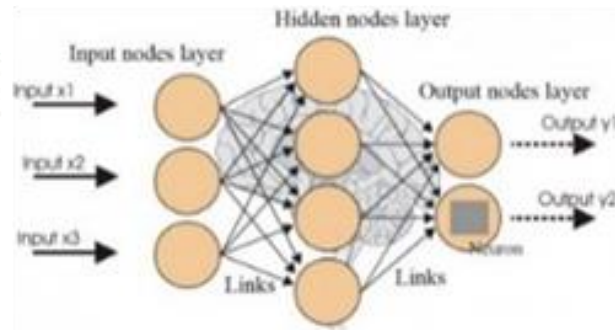
Emulators are statistical models that approximate the processing (input-output) of a physical model (e.g. RTM) - **at a fraction of the computational cost:**

making a statistical model from a physical model

RTM



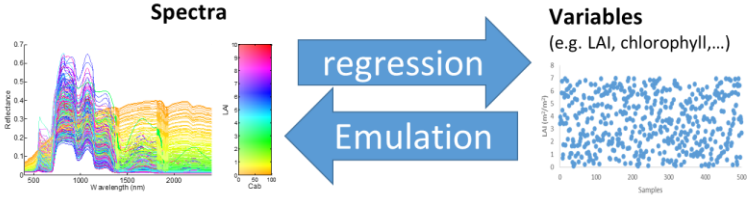
Machine learning



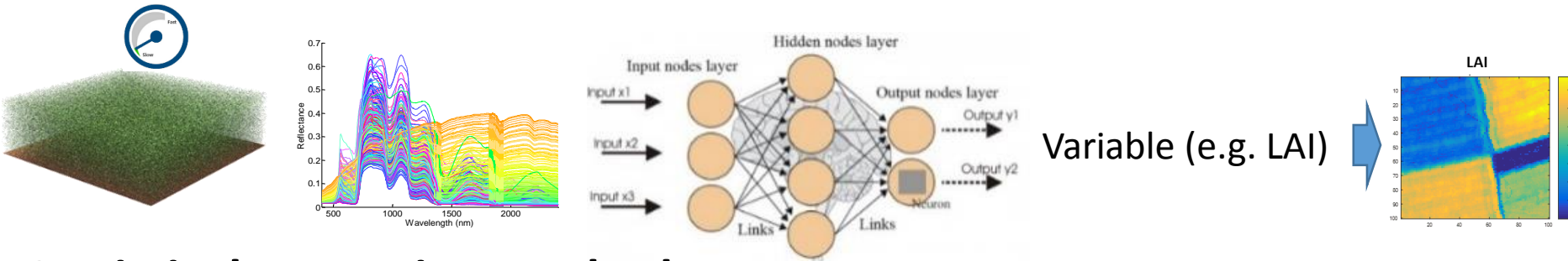
Emulator



Regression vs. Emulation:



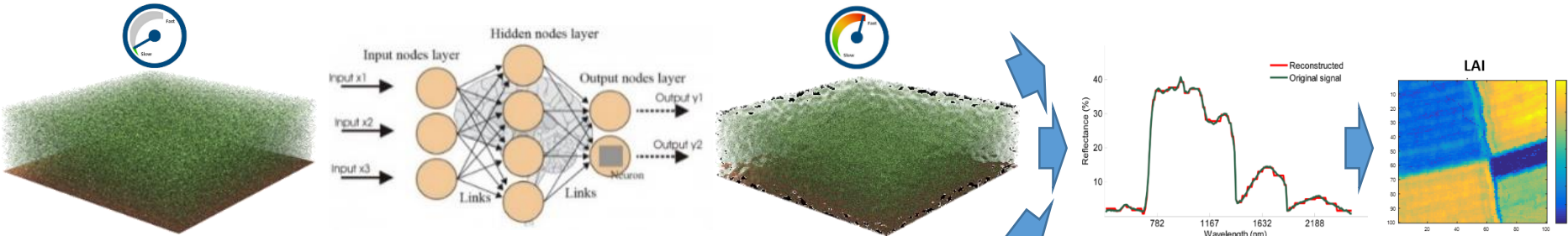
Common use of machine learning in optical RS:



Statistical regression method:

- Variable/data-driven, black box, 1 output, portability is questionable

Emulation in optical RS:



Replace RTM:

- Multiple applications, e.g. inversion
 - ✓ Radiometric method: Spectral fitting
 - ✓ Portable: generally applicable

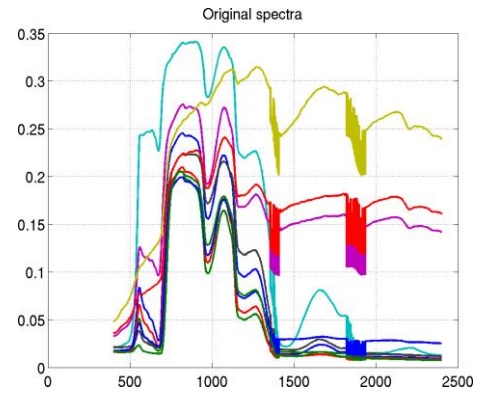


“spectral redundancy” is a blessing

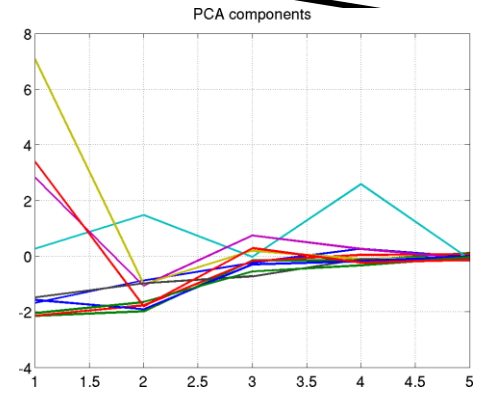
Processing steps emulation



PCA on spectra



$$Sc = U \cdot X$$



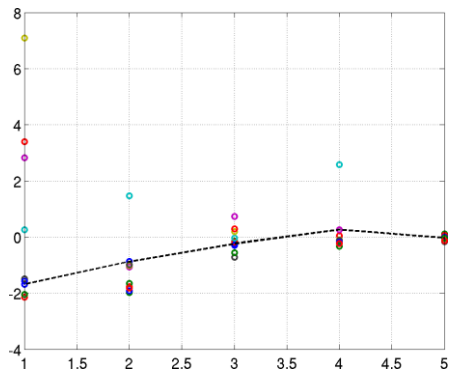
MLRA training looping over components

$$W = (Y + \lambda I)^{-1} \cdot Sc$$

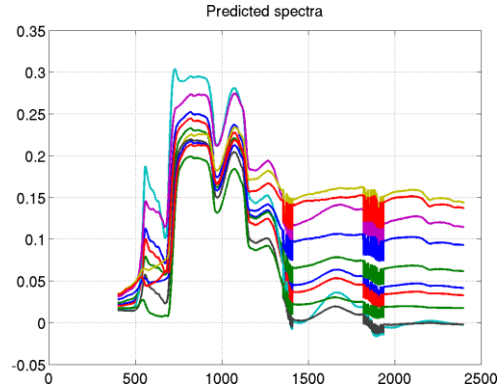
Prediction of components

$$Sp = Sc \cdot W$$

Reconstruction of spectra

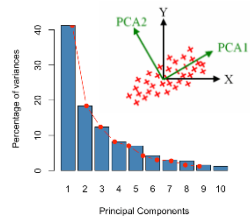
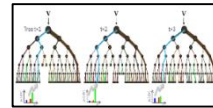
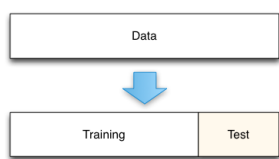
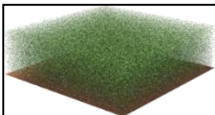


$$Xr = U^T \cdot Sp$$



Emulator toolbox

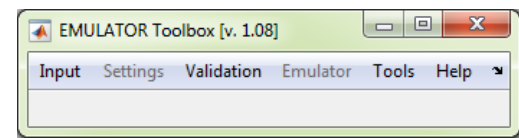
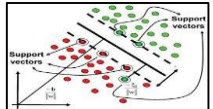
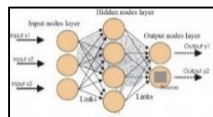
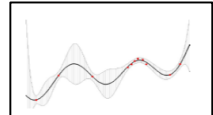
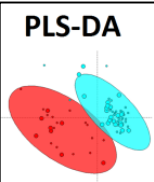
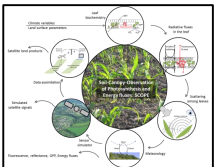
With ARTMO's emulation processing chain any RTM can be converted into an emulator.



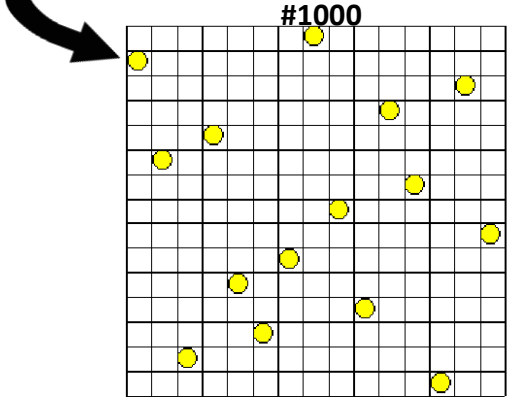
$$Xr = U^T \cdot Sp$$

$$RMSE = \sqrt{\sum \frac{(y_{pred} - y_{ref})^2}{N}}$$

$$NRMSE = \frac{1}{Y_{max} - Y_{min}} \sqrt{\sum_{i=1}^N \frac{(Y_i - \hat{Y}_i)^2}{N}}$$



Latin Hypercube Sampling (LHS)



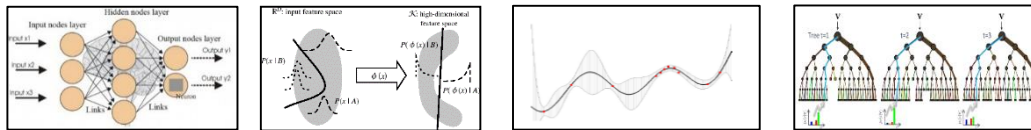
Input RTM data Txt data Select project Edit settings	Settings	Validation New Load	Emulator RTM vs Emulator LUT Emulator Txt Emulator Scene Emulator	Tools Save Load Manage tests Options View figure Plot LUT Residual analyzer Statistical analyzer Import Scene comparison	Help Show Log User's manual Installation guide Disclaimer Delete Rename
---	-----------------	----------------------------------	--	---	--



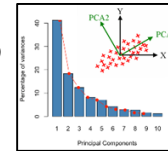


Emulators great idea... what about accuracy?

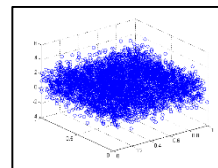
1) Role of machine learning regression algorithm?



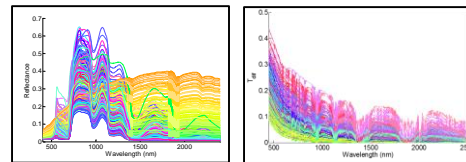
2) Role of dimensionality reduction (DR) method?



3) Role of LUT size training?



4) Role of data type?

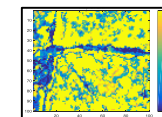
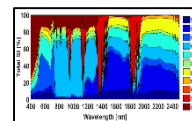
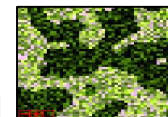
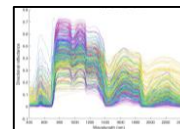


All these factors determine emulation accuracy. Some testing is required*

If OK with losing some accuracy, various applications are opened:

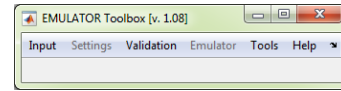
Fast RTM output generation

1. **Fast scene generation**
2. **Fast global sensitivity analysis**
3. **Fast inversion**



* Verrelst, J., Rivera Caicedo, J.P., Muñoz-Marí, J., Camps-Valls, G., Moreno, J. (2017). [SCOPE-Based Emulators for Fast Generation of Synthetic Canopy Reflectance and Sun-Induced Fluorescence Spectra](#). Remote Sensing. 9(9), 927.

Latest developments in Emulator toolbox:



- **New ML algorithms implemented:**

1. Multi-output support vector regression
2. Multi-output Gaussian process regression

 ***In total 9 ML algorithms implemented in toolbox.***

Random Forests (TreeBagger) (RF TB)

Kernel Ridge Regression (KRR)

Random Forests (Fitensembler) (RF FE)

Gaussian Process Regression (GPR)

Neural Network (NN)

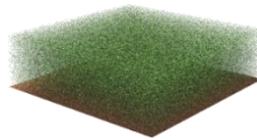
Multi-output GPR (MGPR)

Support Vector Regression (SVR)

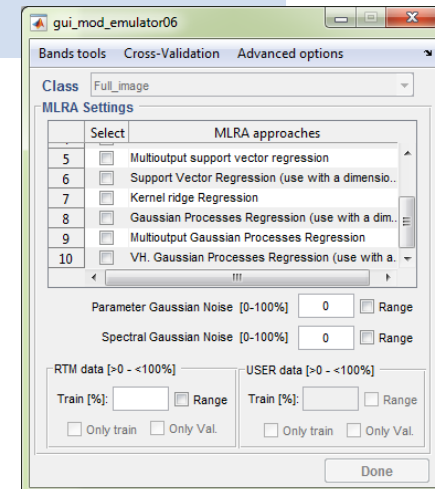
Variational Heteroscedastic GPR (VH GPR)

Multi-output SVR (MSVR)

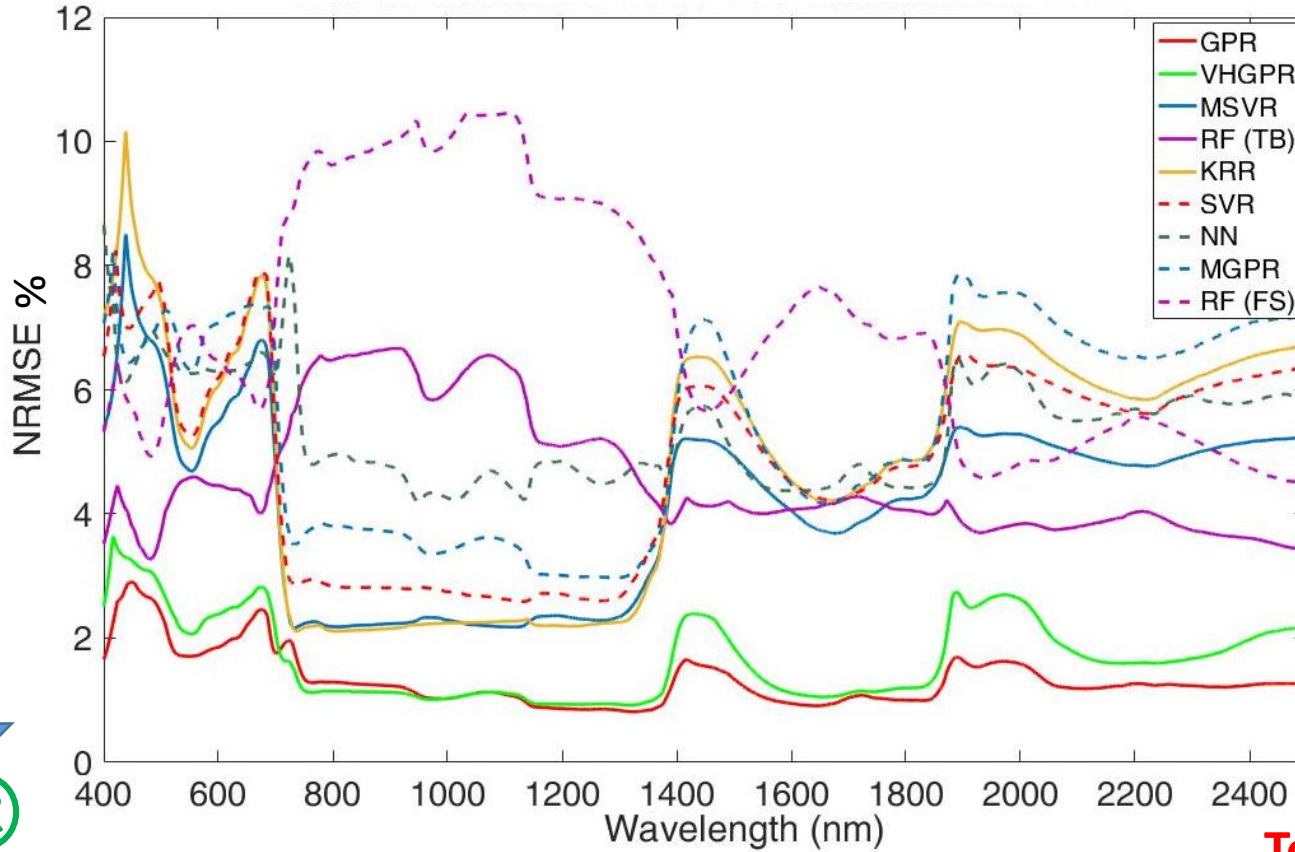
Experimental setup:



- **PROSAIL 1500 LHS** simulations, all variables ranged
- **20 PCA** and 70/30 training-testing data splitting



Performances emulators: accuracy & CPU



MLA	Time train (s) (#1050)
GPR	179
VH.GPR	724
MSVR	52
RF (TB)	32
KRR	4
SVR	2106
NN	42
MGPR	12
RF (FS)	21

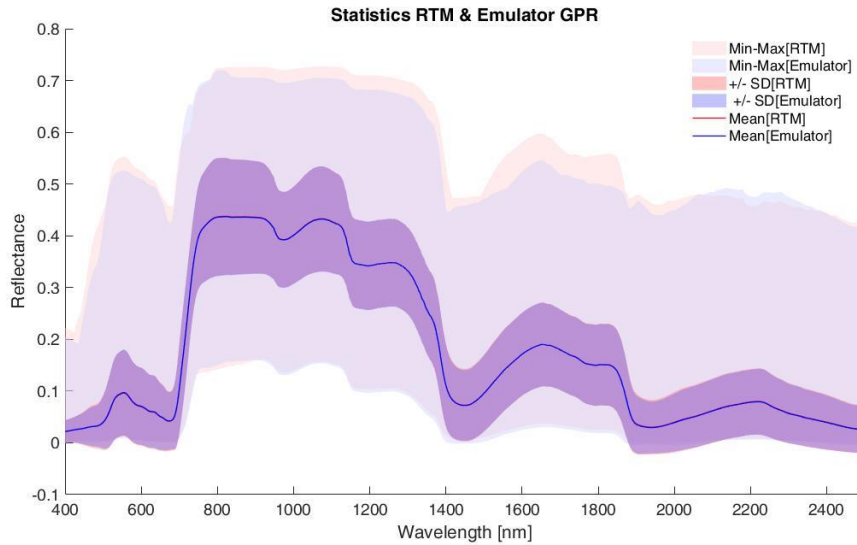
Testing time (#450): <1 s



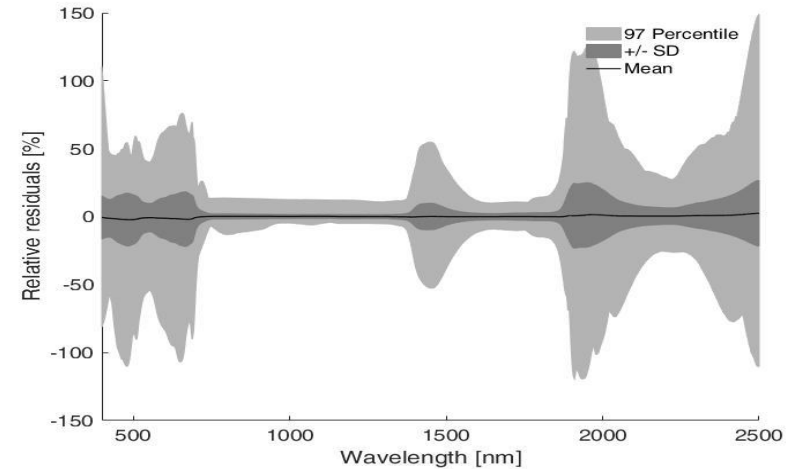
GPR very accurate (<2%)

Validation GPR emulator

Overview statistics emulator vs validation



Residuals



- Mean and SD perfectly matching.
- Some small mismatch in boundaries.

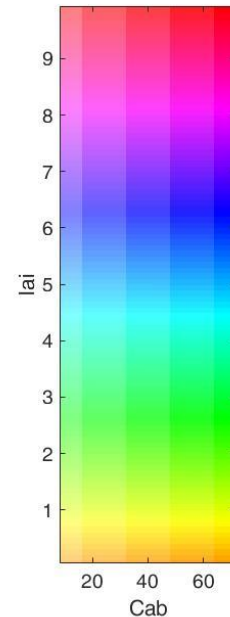
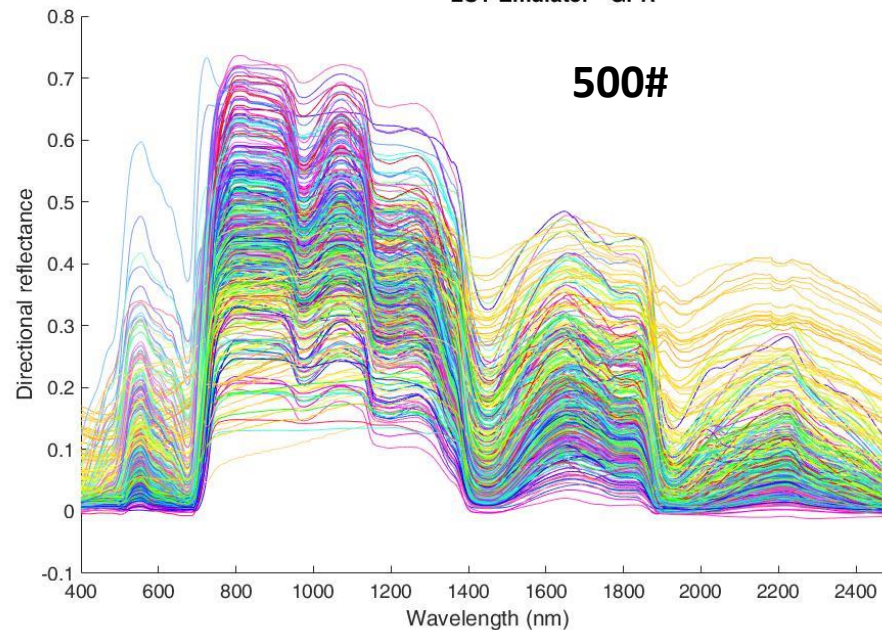


Running GPR emulator:



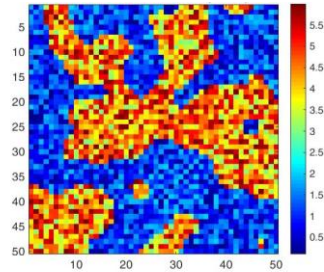
1.0 s

LUT Emulator - GPR



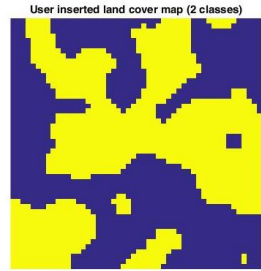
Applications (1/3)

Scene generation

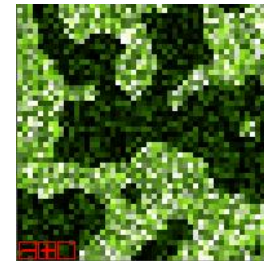
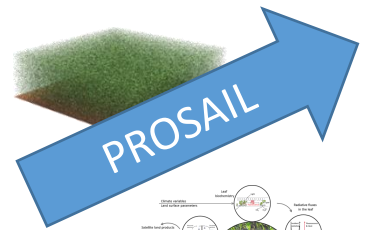
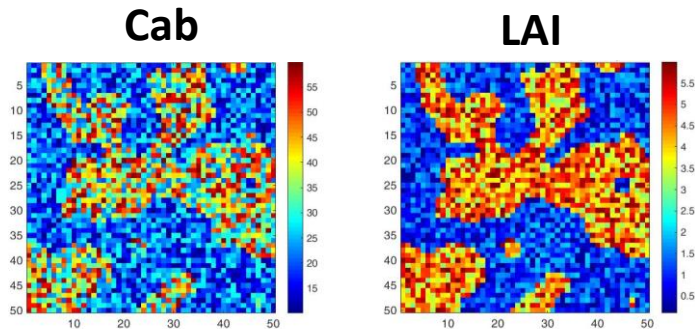


Emulation for Scene generation

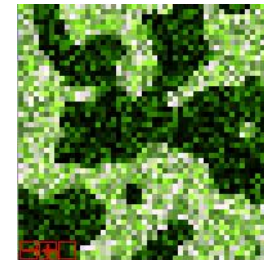
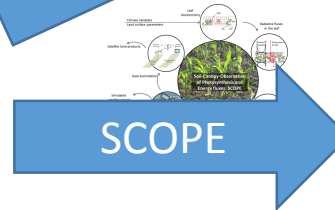
- GPR emulator applied for scene generation
- Compared against RTM scenes: PROSAIL & SCOPE



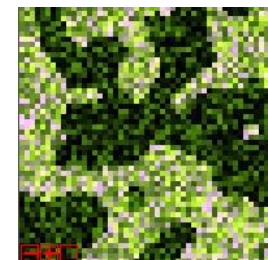
Parameter	Symbol	Units	Class 1	Class 2
Leaf area index	LAI	m ² / m ²	Uniform: 3 - 6	Uniform: 0 - 2
Chlorophyll a+b content	C _{ab}	μg/cm ²	Uniform: 20 - 60	Uniform: 10 - 35



45s



65min



8s

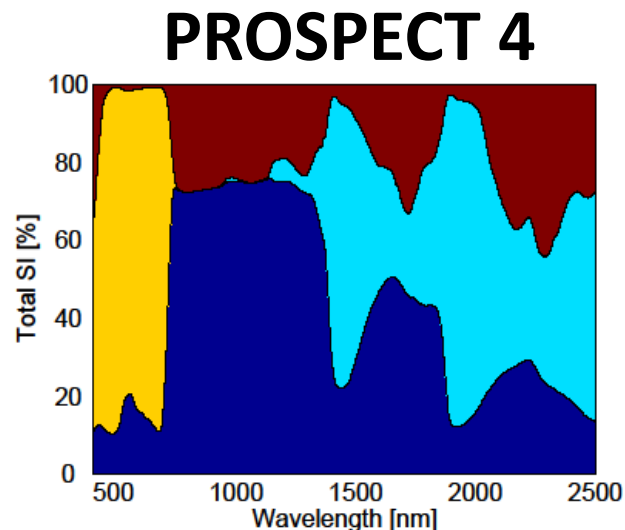


See Talk TU4.R9.5 for emulation of real scenes

Applications (2/3)

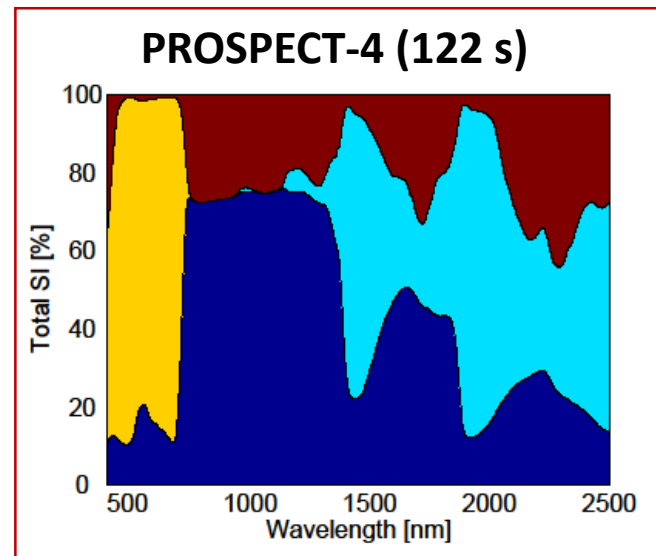
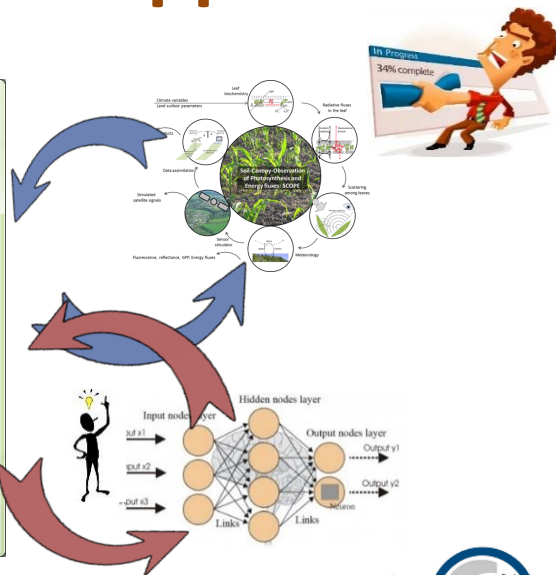
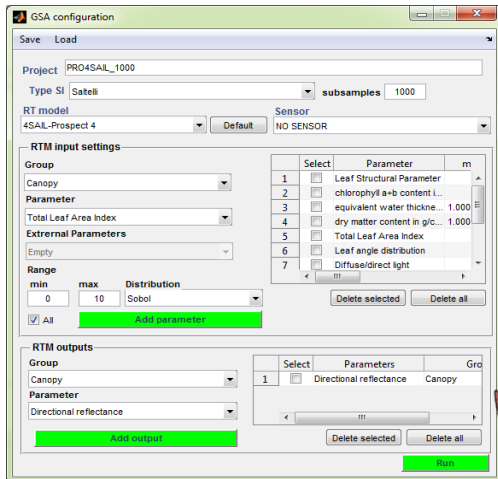
Global Sensitivity Analysis (GSA)

GSA techniques quantify the relative importance of each input parameter to model outputs.



Emulators applied into GSA: PROSPECT-4

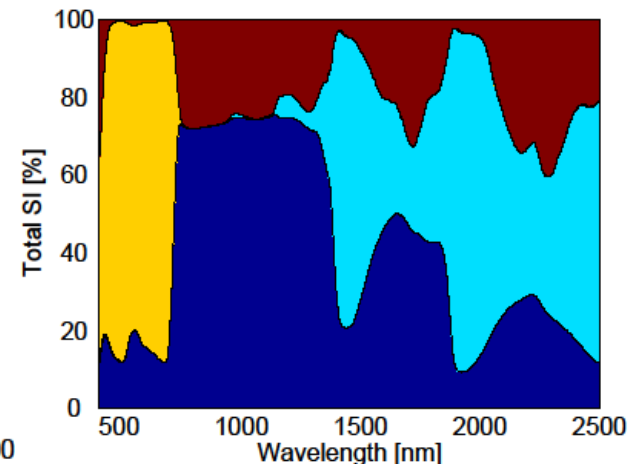
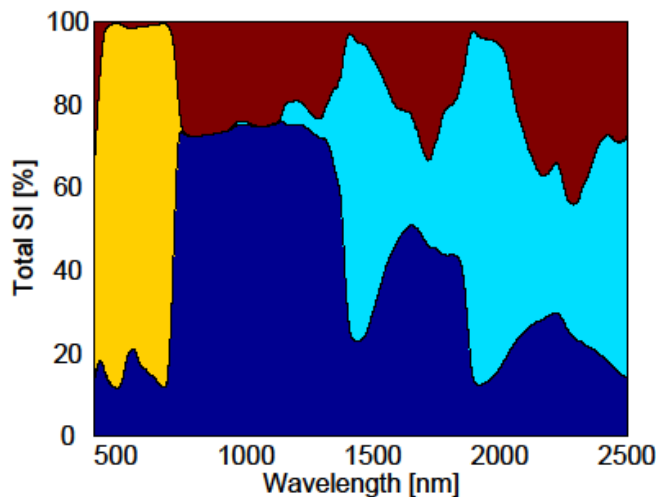
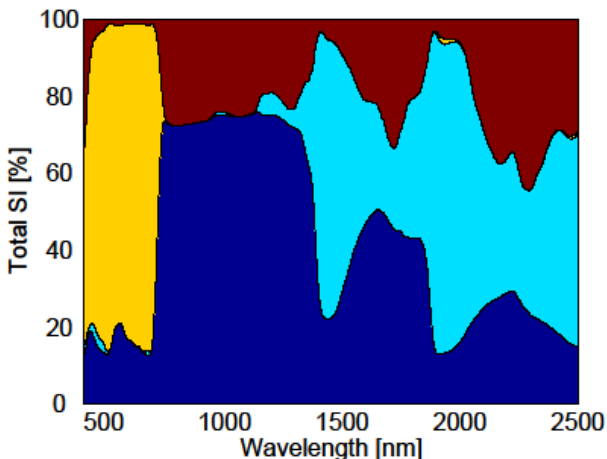
ARTMO's GSA toolbox



KRR (55 s)

NN (55 s)

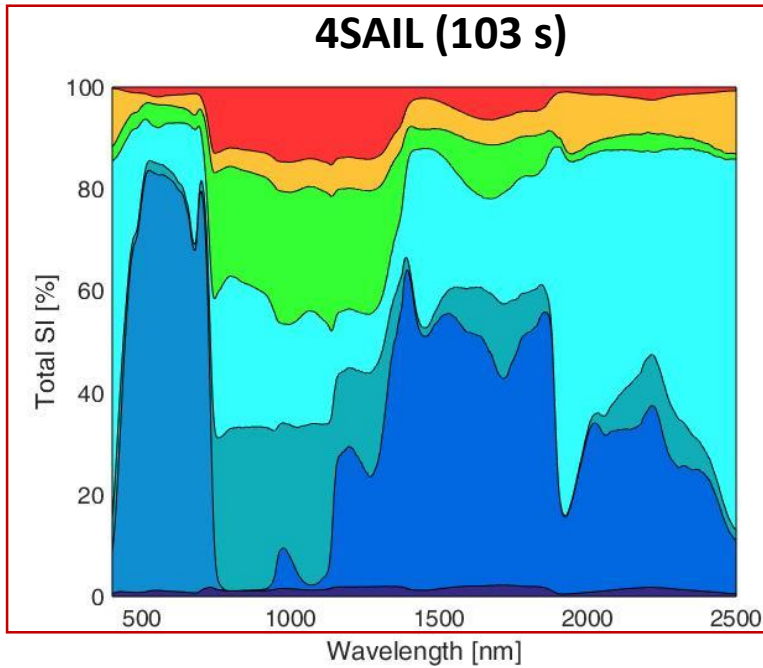
GPR (58 s)



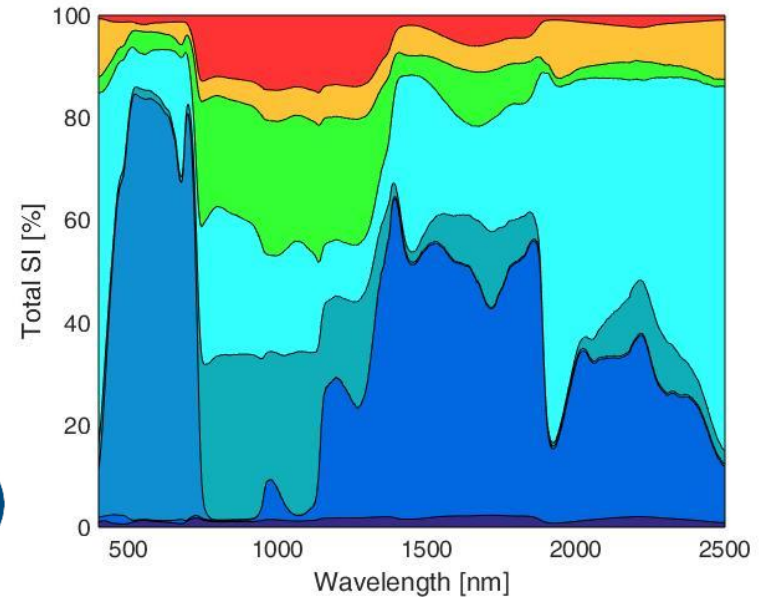
N
 Cw
 Cab
 Cm

PROSAIL

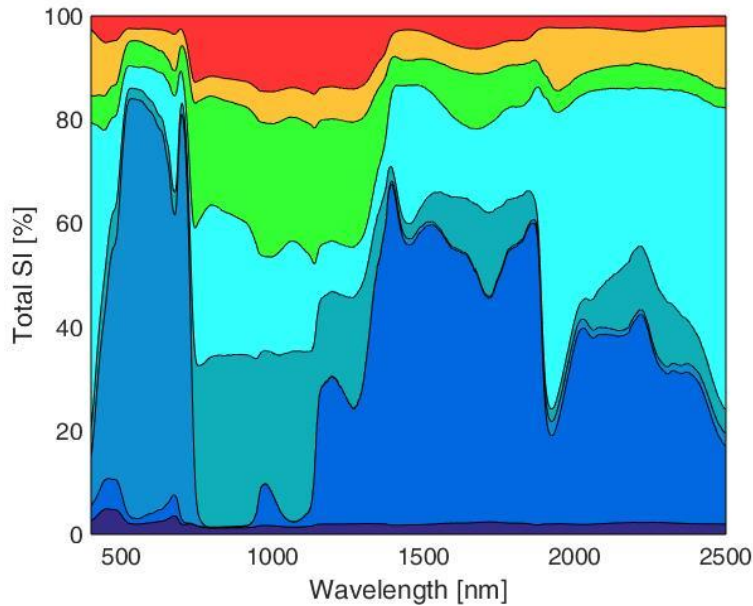
4SAIL (103 s)



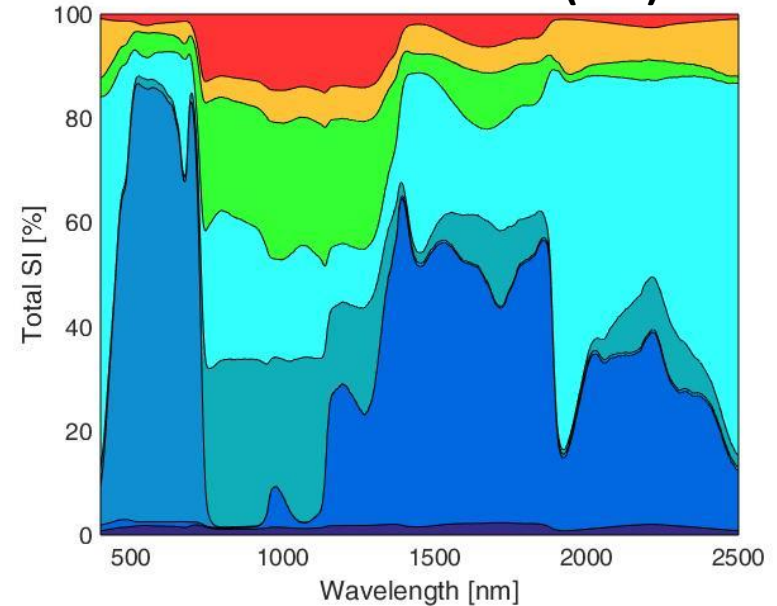
Emulator GPR (32s)



Emulator KRR (28s)



Emulator VHGP (37s)

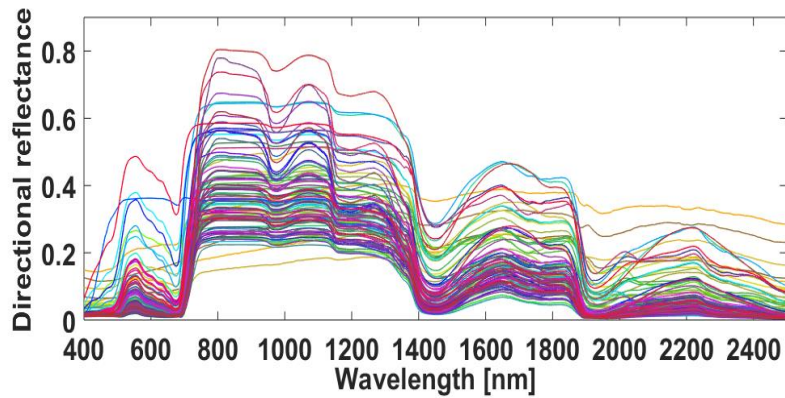


1000#/variable

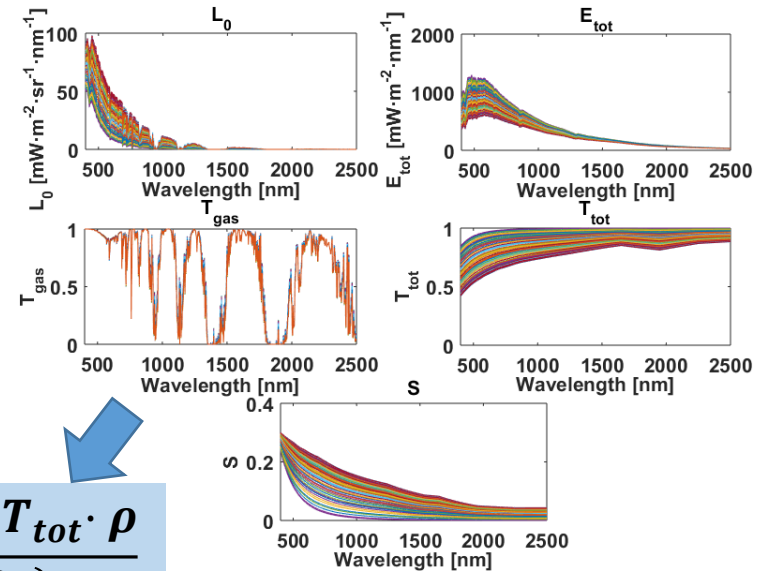
■ N ■ Cw ■ Cab ■ Cm ■ LAI ■ LAD ■ soil coeff ■ SZA

Applying emulation to L_{TOA} (1/3)

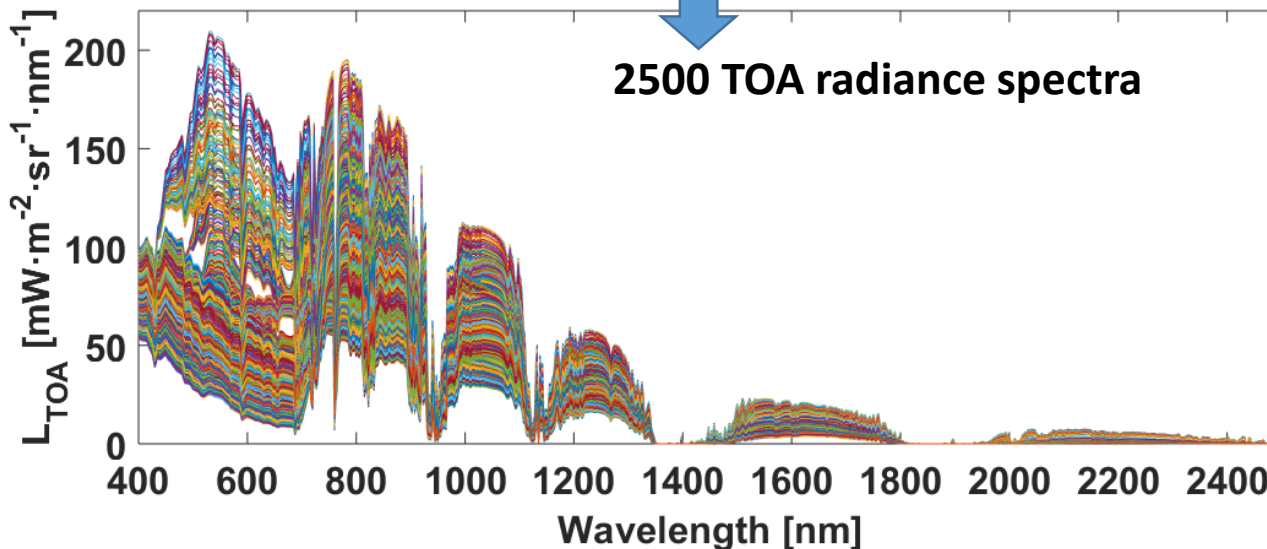
50 PROSAIL spectra



50 6S spectra



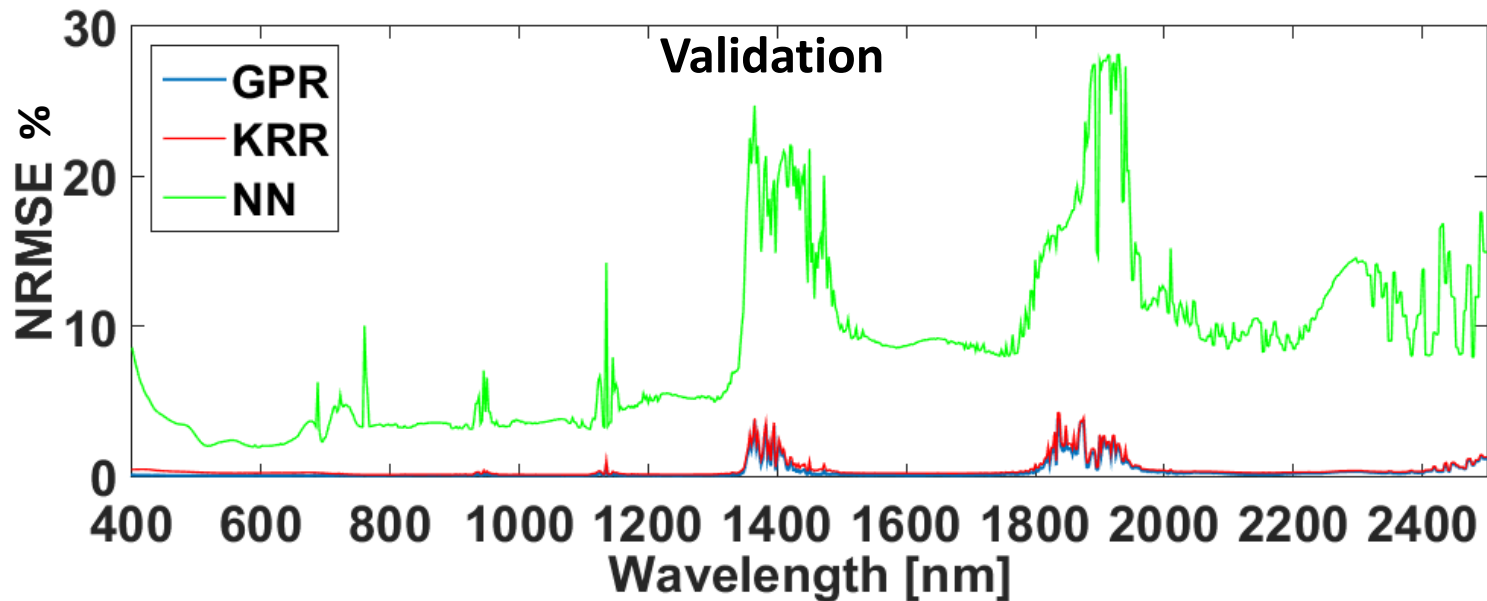
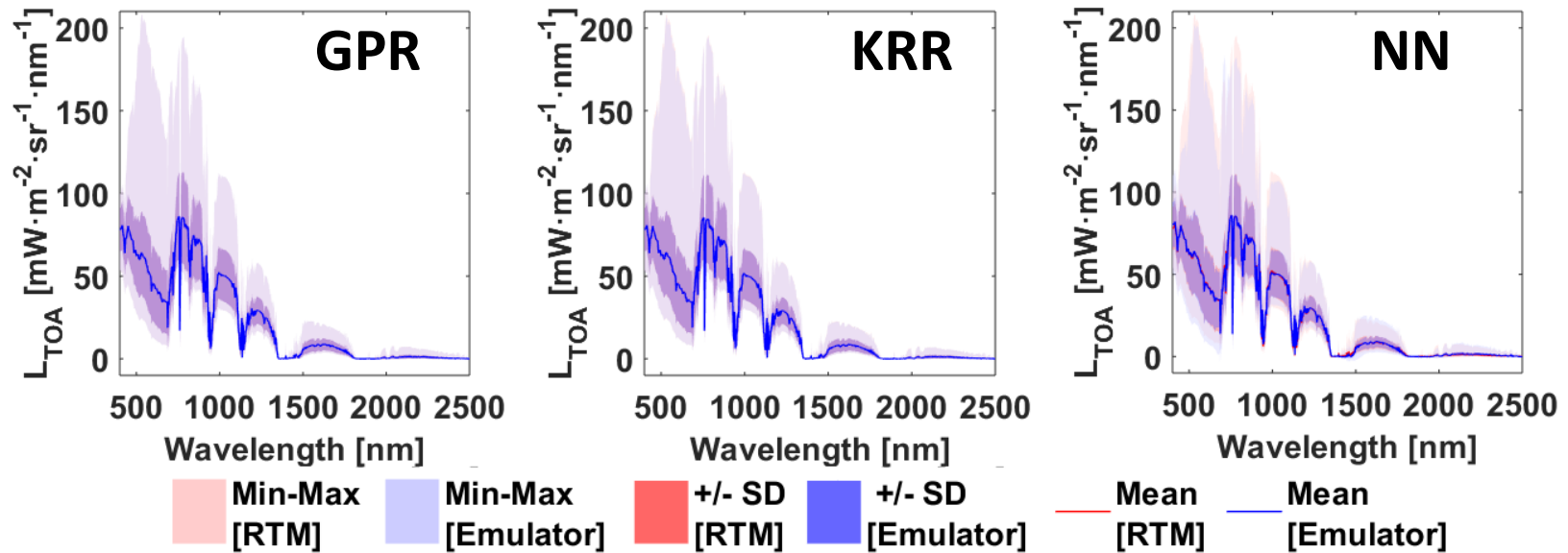
$$L_{TOA} = L_0 + \frac{T_{gas} \cdot E_{tot} \cdot T_{tot} \cdot \rho}{\pi(1 - S\rho)}$$



Emulator

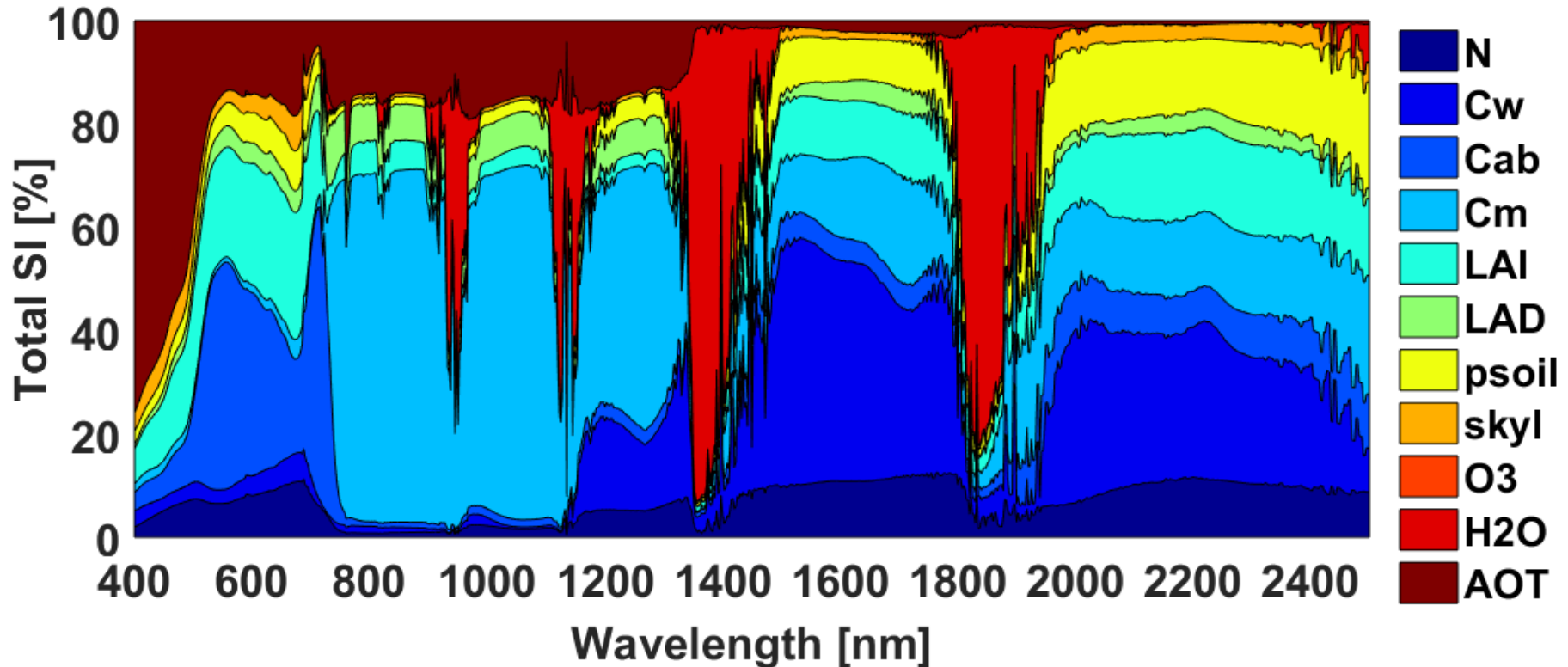
- 30 PCA
- 70/30% train/test

L_{TOA} Emulator results (2/3)



L_{TOA} GSA results GPR emulation (#1000/var) (3/3)

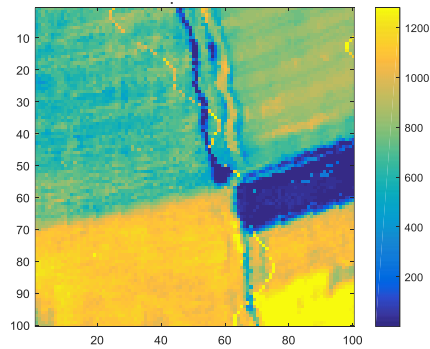
 36 s



- Strong influence of AOT in visible.
- Strong influence of water absorption regions
- SWIR seems attractive for TOA retrieval of vegetation properties (hardly atmospheric effects).

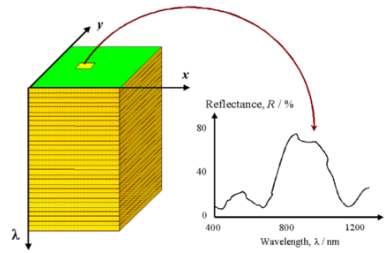
Applications (3/3)

Inversion

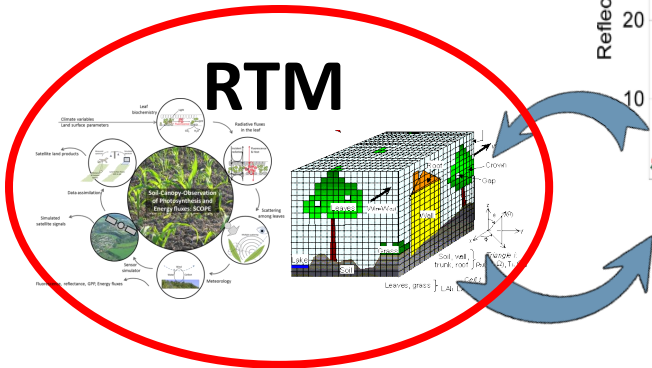


Emulators into numerical inversion

Image



RTM

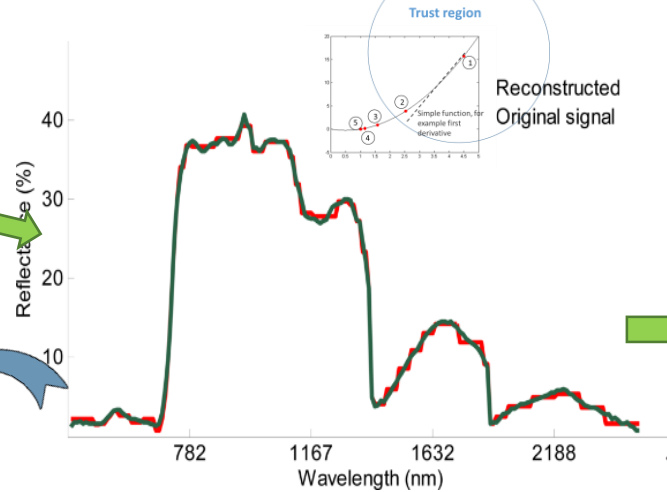


Per-pixel RTM iterations: very slow method, inapplicable to advanced RTMs.

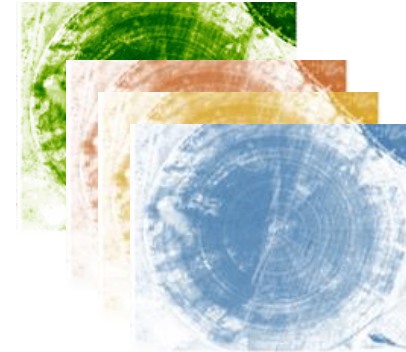


Spectral fitting:

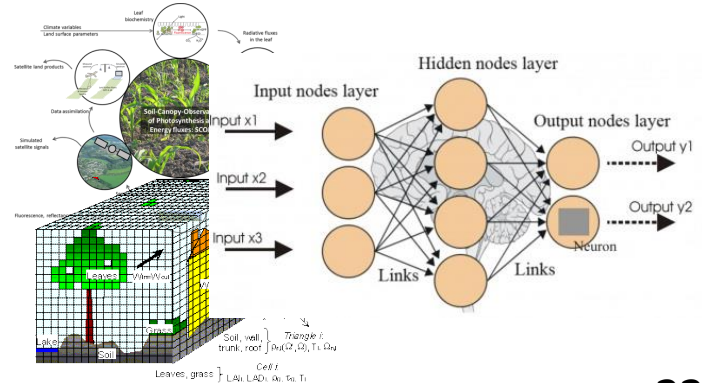
Minimization algorithm: lsqnonlin



Output maps of RTM variables



Emulation of an RTM



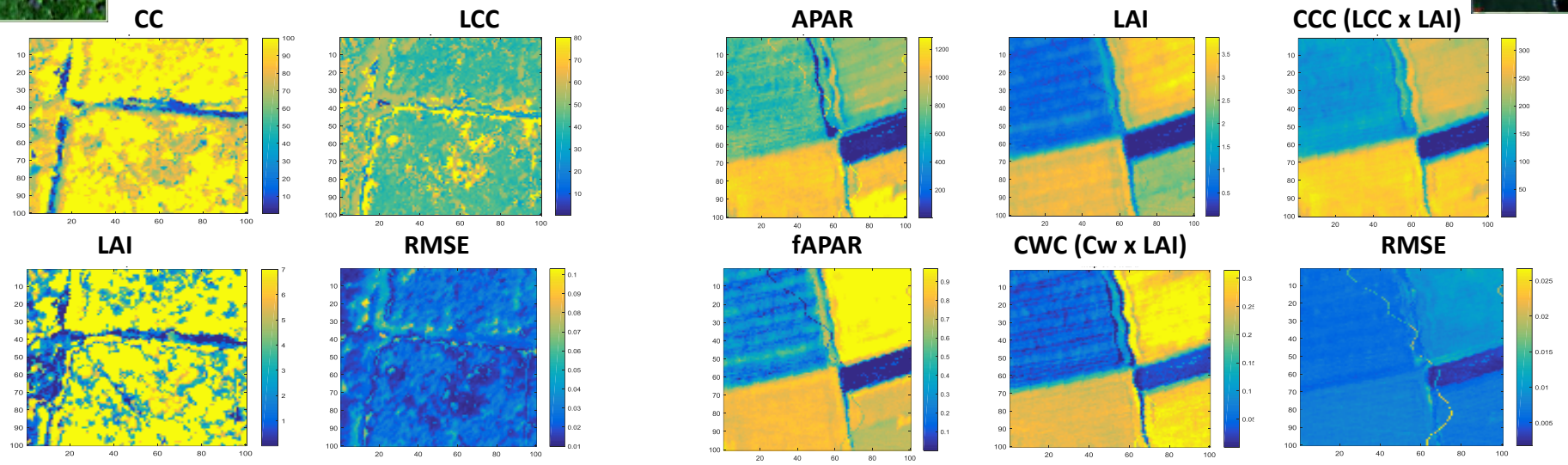
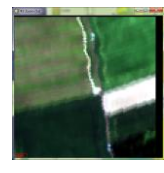
Forest

DART KRR emulator applied to HyPlant DUAL (450-2500 nm)

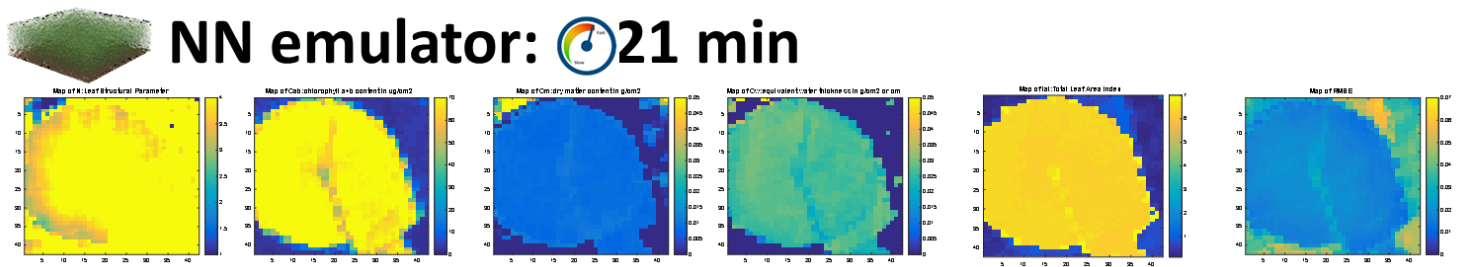
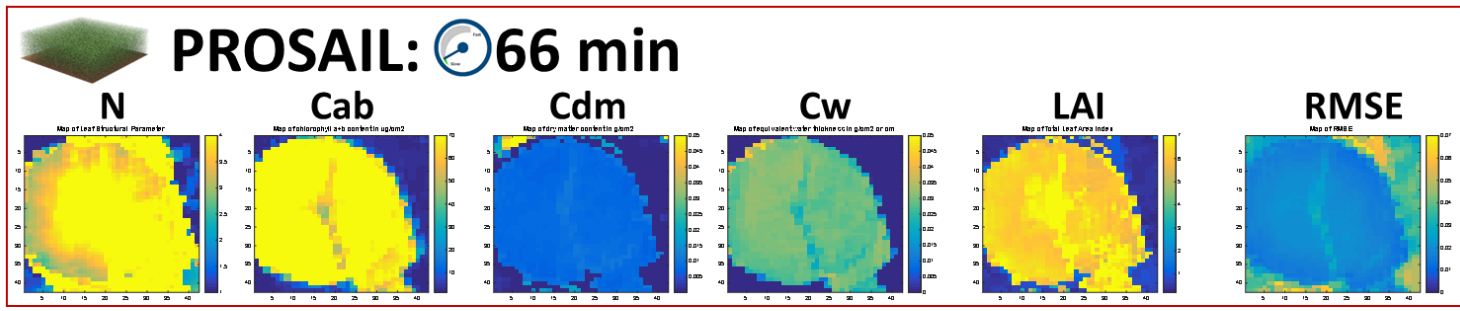
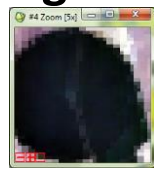
 < 1 h

Agriculture

SCOPE KRR emulator applied HyPlant DUAL (bare soil spectra added)



Agriculture

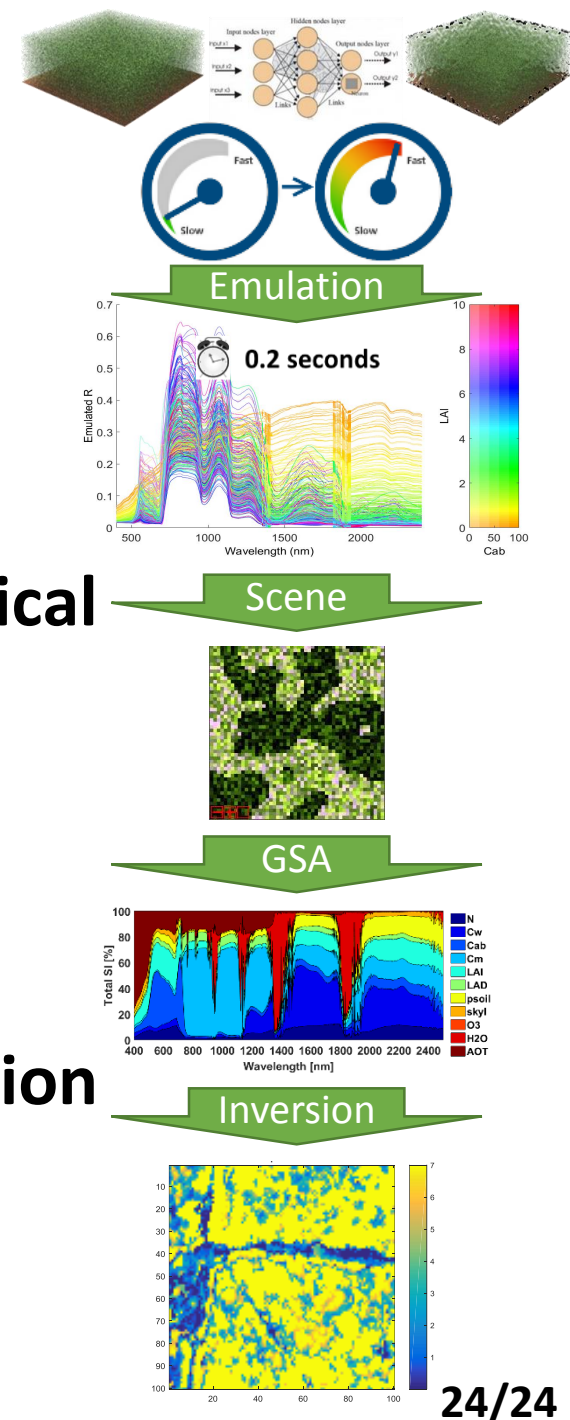



X 3.1

Take home messages

Emulation approximates physical models with sufficient accuracy and tremendous gain in speed.

- ✓ Emulation permits fast rendering of optical images
- ✓ Emulation permits fast calculation of global sensitivity analysis
- ✓ Emulation permits fast numerical inversion of RTM against an image for biophysical variables retrieval



Thanks!



More talks about emulation:



- 1) **Jorge Vicent:** TU1.R7.4: **STATISTICAL LEARNING FOR END-TO-END SIMULATIONS** (09:30 - 09:50)
- 2) **Jochem Verrelst:** TU4.R9.5: **APPROXIMATING EXPERIMENTAL VEGETATION SPECTROSCOPY DATA THROUGH EMULATION** (18:10-18:30)
- 3) **Daniel Heestermans:** WE2.R7.5 **MULTIOUTPUT AUTOMATIC EMULATOR FOR RADIATIVE TRANSFER MODELS** (12:30-12:50)