



ARTMO: a Toolbox for Automated Retrieval of Biophysical parameters through Inversion of Plant Radiative Transfer Models



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1. Introduction

ARTMO, an Automated Radiative Transfer Models Operator toolbox

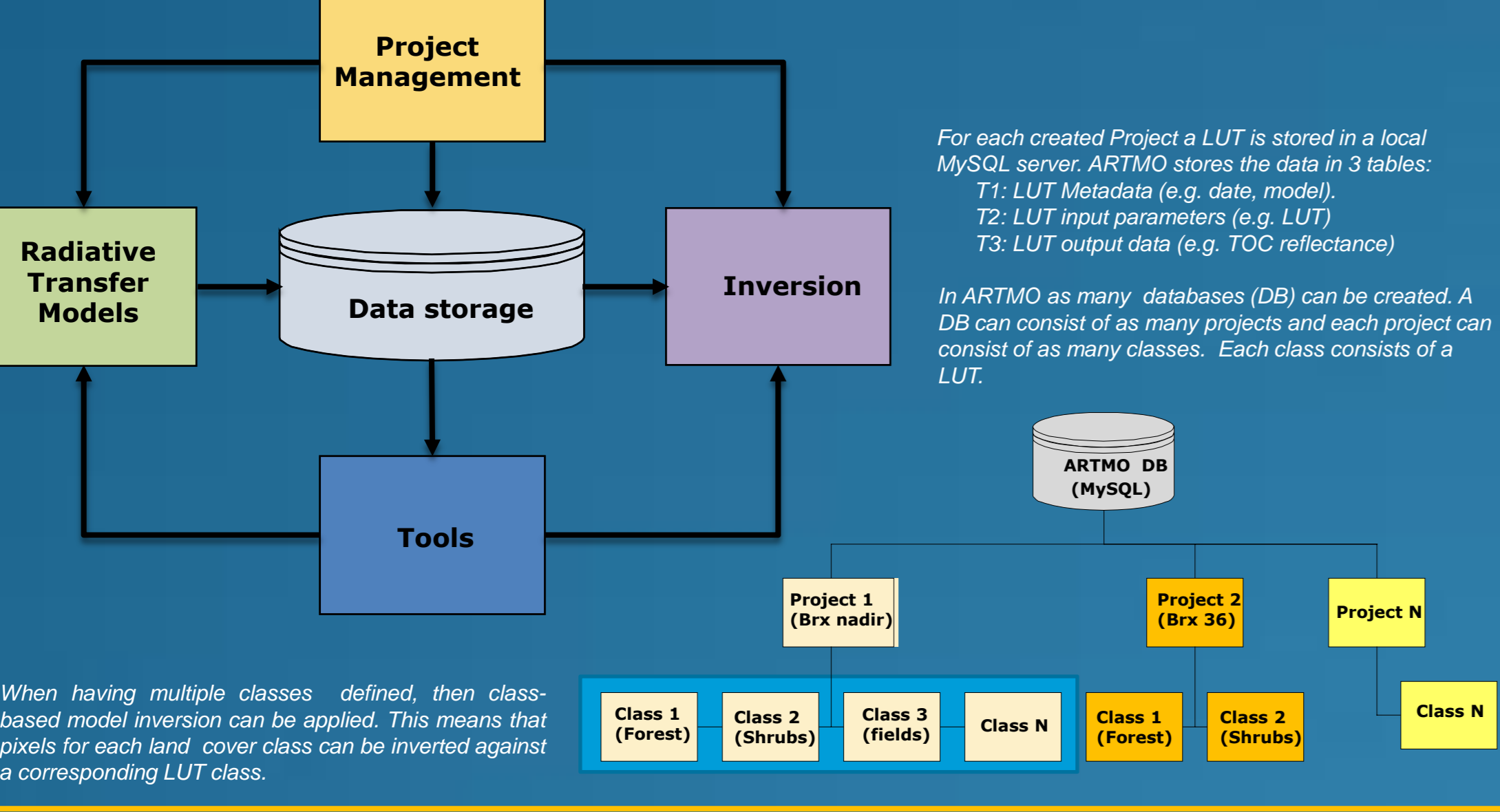
Radiative transfer (RT) models play a key role in earth observation (EO). They are needed to design and develop EO instruments, and to test and apply inversion algorithms. In the scientific community a number of often highly specialized leaf and canopy RT models has been developed, each of which emanates from a different set of original requirements. ARTMO (Automated Radiative Transfer Models Operator) is the first toolbox that brings a variety of leaf and canopy RT models together in one GUI. Moreover, ARTMO encompasses essential tools for EO applications such as defining your own sensor, plotting and exporting outputs and automated LUT-based model inversion. With ARTMO, maps of biophysical parameters can be rapidly derived from EO data. As the toolbox is constantly under development new features are presented here.

Objectives

The aim of this study was to expand ARTMO by offering advanced functions for improved retrieval performances through model inversion. Specifically, the objective was to implement a new inversion module that provides and evaluates a wide range of cost functions. A secondary objective was to test these cost functions against a validation dataset (SPARC; Barrax, Spain).

2. Conceptual design

ARTMO is a toolbox written in Matlab that consists of a package of GUIs. ARTMO incorporates a variety of leaf and canopy radiative transfer models, which can be operated through the creation of 'Projects'. Within a Project, Look Up Tables (LUT) can be created, which are then stored in a MySQL database (DB). These LUTs can then be evoked by various modules such as the Graphics module or the inversion module for further processing. LUT-based inversion against an EO image finally leads to the retrieval of biophysical parameters.



3. ARTMO's main module

Choose stored project from MySQL
Import, export project from MySQL
Possibility to change DB
Selection of classes from a classified map, or
Delete class, project or DB
Defining own user classes

When selecting a sensor, all input data will be automatically resampled to the spectral settings of the selected sensor. This means that any type of spectra (e.g. from field spectrometer or from satellite observations) can be fed into the models (e.g. soil spectra). A warning message appears when ARTMO detects that spectral resampling is required. Any spectral settings can be defined by the user. This is helpful for simulations studies of new or upcoming sensors such as FLEX. Output data is then provided according to chosen sensor.

When a model has been configured it turns active in the 'Run Panel'. Any configured leaf model can be coupled with any configured canopy model. However note that FluorMODleaf needs to be coupled with FluorSAIL to simulate fluorescence emission at canopy level. When clicking on 'Run' then all combinations of the leaf and canopy LUTs will be simulated.

Input, output and meta data are directly stored in a MySQL data server.

On time-consuming tasks, such as forward simulations and inversion calculations, ARTMO provides progress bars of processing time and executed simulations or inverted pixels, respectively.

4. Leaf-level models

ARTMO incorporates the following leaf RT models: PROSPECT4, PROSPECT5 and FluorMODleaf. For each model parameter, a single value, a range of values or an array of user-defined input values can be inserted. All combinations will be simulated.

ARTMO can read in text files with model input values, e.g. coming from field measurements. Data in all kinds of formats can be read. Data columns can be linked to a corresponding parameter. Options to select the required column, to convert data, to skip header and to identify the delimiter character are provided. When a model parameter is being fed by data then this parameter is disabled in the main input window. This parameter can then be combined with inputs of the remaining parameters (single value, range or user-defined values).

Conclusions

ARTMO aims to implement essential models and modules required for terrestrial EO applications in a graphical user interface (GUI) toolbox. ARTMO allows the user:

- i) To choose between various leaf and canopy RT models.
- ii) To choose between spectral band settings of various sensors, or to define own band settings.
- iii) To simulate a massive amount of spectra based on look up tables (LUT) and storing it in a relational database
- iv) To plot simulated spectra of multiple models and compare it with measured spectra.
- v) To evaluate over 50 different cost functions against a validation dataset.
- vi) To run model inversion against airborne or spaceborne images given class-based LUTs, a best-evaluated cost function and accuracy estimates.

Here, the widely used RMSE was not evaluated as best performing cost function when using the SPARC dataset (Barrax, Spain). Also opting for a single best solution appeared to be suboptimal. Taking the average of multiple best solutions and adding noise led to best retrieval results.

5. Canopy-level models

ARTMO incorporates the following canopy models: 4SAIL, FluorSAIL, FLIGHT and then the combined soil-leaf-canopy (SLC) model. Similar to the leaf models, for each parameter, a single value, a range or a text file with user-defined values can be inserted. Further, in contrary to leaf models, canopy models need spectral inputs for their elements such as leaves, soil, bark and senescent leaves. Therefore, for each model spectral data can be inserted by clicking on the associated name in the top bar. An input window will appear. When also a leaf model has been configured then those simulated spectra will be used as leaf spectral input into the canopy model. Multiple spectra of other elements can be inserted which then form part in building up the LUT.

6. LUT access and metadata

In ARTMO's 'Project Overview' window an overview of all created projects and classes within the current DB are displayed. This 'Project Overview' can be accessed from ARTMO's main module (click on 'Load Project') or via the 'Graphics' or 'Inversion' modules. The top panel shows all Projects from the current DB along with its metadata such as date of creation, sensor, number of bands, classes and simulations. By clicking on one of the projects then in the middle panel its included classes are shown along with its metadata such as date of creation, used models, class name and number of simulations. Each class consists of a LUT. By clicking on a class then in the down panels then both at leaf level as at canopy level the complete LUT configurations and fixed parameters appear.

7. Graphics module

In ARTMO's 'Graphics' module simulated LUTs can be plotted and exported to a text file for further use. Multiple groups of output spectra, e.g. originating from different LUTs, can be plotted within the same plotting window. As such the output spectra from different models can be directly compared.

8. Inversion module

ARTMO's most advanced module is the 'Inversion' module. This module enables automated mapping of biophysical parameters from multispectral or hyperspectral imagery based on pre-computed LUTs. Several cost functions and optimization options are provided. Most importantly, inversion can be done class-based. This means that different land cover classes can be linked to different LUTs. For instance, homogeneous land covers such as agricultural fields can be interpreted by a turbid model (e.g. SAIL) while heterogeneous land covers such as forests can be interpreted by a 3D model (e.g. FLIGHT).

9. Provided cost functions

1. Information Measures
In order to apply some classes of distances from discrete distributions we assume that the reflectance data are normalized in the following way, where $R^+(x, \lambda)$ is satellite reflectance and $R^-(x, \lambda)$ is LUT reflectance.
 $R^+(x, \lambda) \in A$ and for $1 \leq i \leq N$ we introduce
 $O = (o_1, \dots, o_N) = \frac{R^+(x, \lambda)}{\sum_{i=1}^N R^+(x, \lambda)}$ and $P = (p_1, \dots, p_N) = \frac{R^-(x, \lambda)}{\sum_{i=1}^N R^-(x, \lambda)}$
and $\sum_{i=1}^N p_i = 1$
The class of distances can be written as follows: (for a given strictly convex twice-differential function f we define:
 $f(P, Q) = \sum_{i=1}^N f\left(\frac{p_i}{q_i}\right) \cdot q_i$
 $f(P, Q) \rightarrow \min_{P \in \mathcal{P}} f(P, Q)$
We approximate $f(x)$ by parametric family $f(x) = \log(x) + \frac{1}{2} \log(x^2 + 1)$ and a minimum contrast estimator minimizes
 $D_{f, P, Q}(x) = \sum_{i=1}^N [f\left(\frac{p_i}{q_i}\right) + f\left(\frac{q_i}{p_i}\right)] \cdot q_i$
Function $D_{f, P, Q}(x)$ should be a three times continuously differentiable on $(0, \infty)$ and has a unique minimum at $x = 1$.
 $D_{f, P, Q}(x) \geq 0$ for $f(x) \geq 0$.

2. Minimum Contrast Estimates
Let Z be a stationary or homogeneous stochastic process with mean m and true spectral density $\phi(\lambda)$ (in our case satellite reflectance). Indeed the observations can be represented in the spectral domain in the form of the periodogram $I_n(\lambda, Z)$.
 $I_n(\lambda, Z) = \frac{1}{n} \left| \sum_{k=0}^{n-1} Z_k e^{-i\lambda k} \right|^2$
We approximate $I_n(\lambda, Z)$ by parametric family $I_n(\lambda, Z) = \frac{1}{n} \sum_{k=0}^{n-1} Z_k e^{-i\lambda k}$ and a minimum contrast estimator minimizes
 $D_{f, P, Q}(x) = \sum_{i=1}^N [f\left(\frac{p_i}{q_i}\right) + f\left(\frac{q_i}{p_i}\right)] \cdot q_i$
Function $D_{f, P, Q}(x)$ should be a three times continuously differentiable on $(0, \infty)$ and has a unique minimum at $x = 1$.
 $D_{f, P, Q}(x) \geq 0$ for $f(x) \geq 0$.

Examples
1. Bergman non-symmetric distance
 $f(x) = \log(x) + \frac{1}{2} \log(x^2 + 1)$
2. Shannon and Mitter (1975), $\alpha = 0.5$
 $f(x) = \log(x) + \frac{1}{2} \log(x^2 + 1)$
3. Sharma and Mittal (1975), $\alpha = 0.5, \beta = 1$
 $f(x) = \log(x) + \frac{1}{2} \log(x^2 + 1) + \frac{1}{2} \log(x^2 + 1)$
4. Sharma and Mittal (1975), $\alpha = 0.5, \beta = 1$
 $f(x) = \log(x) + \frac{1}{2} \log(x^2 + 1) + \frac{1}{2} \log(x^2 + 1)$

'Information measures'
we assume that our reflectance is some probability distribution and we compare 'metrics' between two distribution functions.
In total we included about 50 different Information Measures in ARTMO. Although many perform similarly, quite some of them seem to perform better than the widely used RMSE.

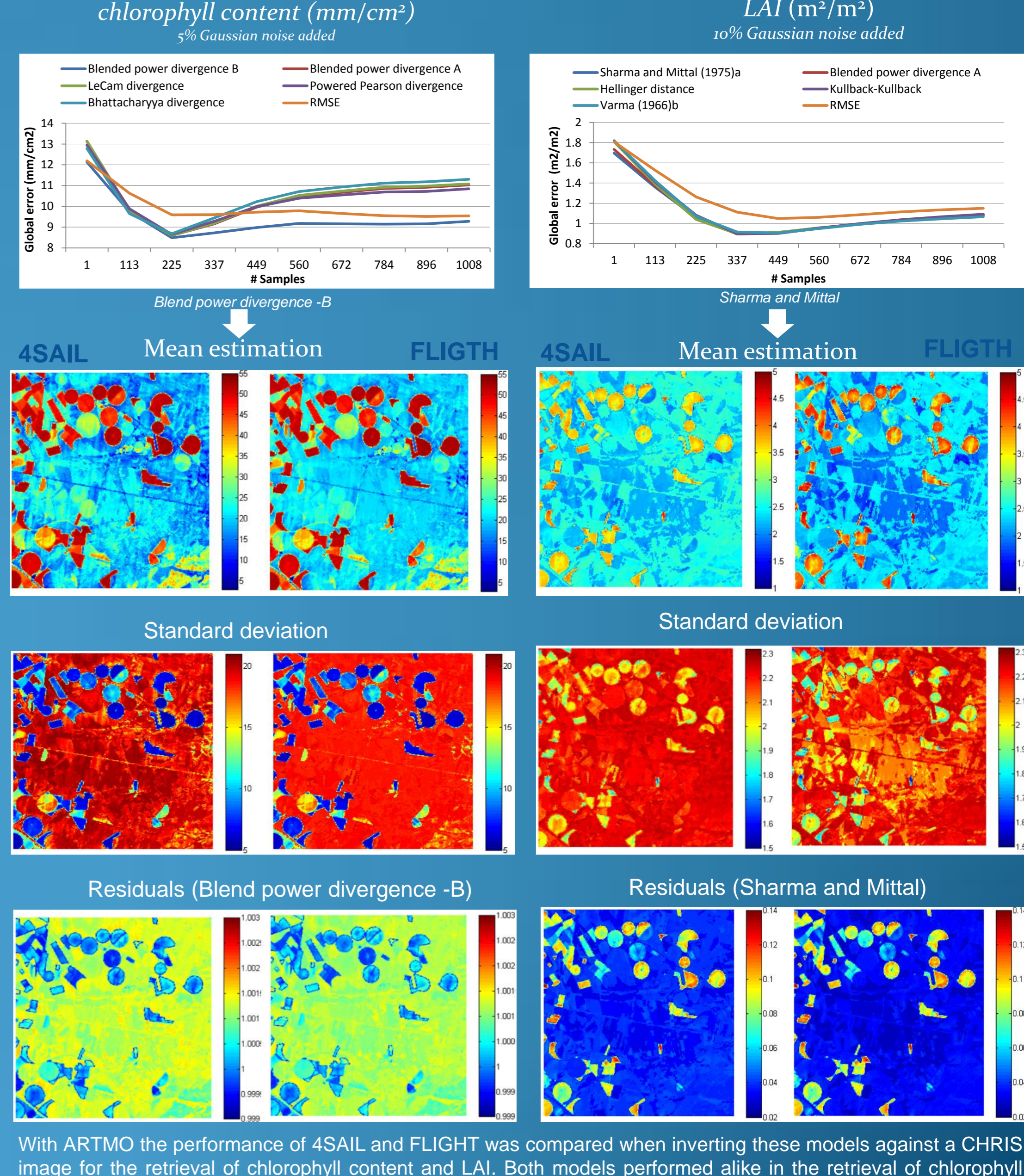
'Minimum Contrast estimate'
we assume that reflectance function is a spectral probability density function.
We are currently working on adding yet another family of distance functions 'M-estimates'. These are measures of location that are not as sensitive as the mean to outlier values.

10. ARTMO's Cost functions evaluator

ARTMO offers the possibility to evaluate the range of included cost functions against validation data.

11. Results

By inputting a validation dataset (SPARC, Barrax, 2003) into ARTMO's cost function evaluator, all selected cost functions were evaluated. In the figures below the best 5 performing functions and additionally the commonly used RMSE are plotted. At X-axis, starting from the single best solution, the average of multiple best solutions is shown. It can be noted that not the single best solution led to best performances, but rather the average of a few hundred best solutions. It can also be observed that RMSE was neither for chlorophyll content (Chl) nor for LAI evaluated as best performing cost function. Nevertheless, the best performing function also depends on the used parameter. For Chl the 'Blend power divergence-B' led to best inversion performance, while for LAI the 'Sharma and Mittal' led to best inversion performance. It was also found that adding Gaussian noise improved accuracies.



With ARTMO the performance of 4SAIL and FLIGHT was compared when inverting these models against a CHRIS image for the retrieval of chlorophyll content and LAI. Both models performed alike in the retrieval of chlorophyll content, probably because they used the same PROSPECT model. However, no variation in LAI was observed when inverting FLIGHT. This can probably be explained by the different nature of FLIGHT (3D ray tracing model) as compared to SAIL (turbid medium model).